



Re: SMITH, Graham Thomas and FELS, Deborah Ingrid and
TREVIRANUS, Jutta
Patent Application in the U.S.
Serial No. : 09/423414 Filing Date: May 6, 1998
Our Case : P150299
Title: Teleconferencing Robot With Swiveling Video Monitor
Response Due: March 15, 2003
1-MONTH EXTENSION DUE DATE: April 15, 2003

CLEAN COPY OF AMENDED CLAIMS

Subj 1. A teleconferencing robot, for enabling a remote conferee to project a sense of presence into a group meeting, said remote conferee located remotely from said group meeting, the teleconferencing robot comprising:

a base;
a video monitor movably mounted to the base for receiving and displaying an image of the remote conferee;

a video camera movably mounted on the base;
control means mounted on the base for moving the video monitor and video camera in response to an input control signal derived from a remote signal generated by the remote conferee; and

wherein said video monitor and video camera move in response to said input control signal to enable the remote conferee to project a sense of presence into the group meeting.

Subj 6. A teleconferencing robot as claimed in claim 1, wherein said input control signal is optionally derived from sound source detection means such that said control signal represents the direction of said sound source with respect to said monitor and said control means being adapted to drive said video monitor, in response to said control signal, to a position substantially facing said detected direction.

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21. (new) A teleconferencing robot, for enabling a remote conferee to project a sense of presence into a group meeting, said remote conferee located remotely from said group meeting, the teleconferencing robot comprising:

a base;

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a video monitor movably mounted to the base for receiving and displaying an image of the remote conferee;

a video camera;

control means mounted on the base for moving the video monitor in response to an input control signal derived from a remote signal generated by the remote conferee; and

wherein said video monitor move in response to said input control signal to enable the remote conferee to project a sense of presence into the group meeting.
